## TESTING COMMUNITY STRUCTURE FOR HYPERGRAPHS

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Many complex networks in the real world can be formulated as hypergraphs where community detection has been widely used. However, the fundamental question of whether communities exist or not in an observed hypergraph remains unclear. This work aims to tackle this important problem. Specifically, we systematically study when a hypergraph with community structure can be successfully distinguished from its Erdős-Rényi counterpart, and propose concrete test statistics when the models are distinguishable. The main contribution of this paper is threefold. First, we discover a phase transition in the hyperedge probability for distinguishability. Second, in the bounded-degree regime, we derive a sharp signal-to-noise ratio (SNR) threshold for distinguishability in the special two-community 3uniform hypergraphs, and derive nearly tight SNR thresholds in the general two-community m-uniform hypergraphs. Third, in the dense regime, we propose a computationally feasible test based on sub-hypergraph counts, obtain its asymptotic distribution, and analyze its power. Our results are further extended to nonuniform hypergraphs in which a new test involving both edge and hyperedge information is proposed. The proofs rely on Janson's contiguity theory (Combin. Probab. Comput. 4 (1995) 369-405), a high-moments driven asymptotic normality result by Gao and Wormald (Probab. Theory Related Fields 130 (2004) 368–376), and a truncation technique for analyzing the likelihood ratio.

**1. Introduction.** Community detection is a fundamental problem in network data analysis. For instance, in social networks [24, 34, 58], protein to protein interactions [16], image segmentation [52], among others, many algorithms have been developed for identifying community structure. Theoretical studies on community detection have mostly been focusing on ordinary graph setting in which each possible edge contains exactly two vertices (see [4, 7, 13, 28, 50, 58, 59]). One common assumption made in these references is the existence of communities. Recently, a number of researchers have been devoted to testing this assumption, for example, [9, 10, 12, 26, 27, 40, 43, 55]. Besides, hypothesis testing has been used to test the number of communities in a network [12, 40].

Real-world networks are usually more complex than ordinary graphs. Unlike ordinary graphs where the data structure is typically unique, for example, edges only contain two vertices, *hypergraphs* demonstrate a number of possibly overlapping data structures. For instance, in coauthorship networks [22, 47–49], the number of coauthors varies across different papers so that one cannot consider edges consisting of two coauthors only. Instead, a new type of "edge," called *hyperedge*, must be considered which allows the connectivity of arbitrarily many coauthors. The complex structures of hypergraphs create new challenges in both theoretical and methodological studies. As far as we know, existing hypergraph literature mostly focuses on community detection in algorithmic aspects [4, 13, 17, 31, 39, 41,

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50, 51]. Only recently, Ghoshdastidar and Dukkipati [31, 32] provided a statistical study in which a spectral algorithm based on adjacency tensor was proposed for identifying community structure and asymptotic results were developed. Nonetheless, the important problem of testing the existence of community structure in an observed hypergraph remains untreated.

In this paper, we aim to tackle the problem of testing community structure for hypergraphs. We first consider the relatively simpler but widely used uniform hypergraphs in which each hyperedge consists of an equal number of vertices. For instance, the (user, resource, annotation) structure in folksonomy may be represented as a uniform hypergraph where each hyperedge consists of three vertices [30]; the (user, remote host, login time, logout time) structure in the login-data can be modeled as a uniform hypergraph where each hyperedge contains four vertices [33]; the point-set matching problem is usually formulated as identifying a strongly connected component in a uniform hypergraph [17]. We provide various theoretical or methodological studies ranging from dense uniform hypergraphs to sparse ones and investigate the possibility of a successful test in each scenario. Our testing results in the dense case are then extended to the more general nonuniform hypergraph setting, in which a new test statistic involving both edge and hyperedge is proposed. One important finding is that our new test is more powerful than the classic one involving edge information only, showing the advantage of using hyperedge information to boost the testing performance. A more notable contribution is a nearly tight threshold for signal-to-noise ratio to examine the existence of community structure (Theorem 2.6).

1.1. Review of hypergraph model and relevant literature. In this section, we review some basic notions in hypergraphs and recent progress in the literature. Let us first review the notion of the uniform hypergraph. An *m-uniform hypergraph*  $\mathcal{H}_m = (\mathcal{V}, \mathcal{E})$  consists of a vertex set  $\mathcal{V}$  and a hyperedge set  $\mathcal{E}$ , where each hyperedge in  $\mathcal{E}$  is a subset of  $\mathcal{V}$  consisting of exactly m vertices. Two hyperedges are the same if they are equal as vertex sets. An l-cycle in  $\mathcal{H}_m$  is a cyclic ordering  $\{v_1, v_2, \ldots, v_r\}$  of a subset of the vertex set with hyperedges like  $\{v_i, v_{i+1}, \ldots, v_{i+m-1}\}$  and any two adjacent hyperedges have exactly l common vertices. An l-cycle is loose if l=1 and tight if l=m-1. To better illustrate the notion, consider a 3-uniform hypergraph  $\mathcal{H}_3 = (\mathcal{V}, \mathcal{E})$ , where  $\mathcal{V} = \{v_1, v_2, v_3, v_4, v_5, v_6, v_7\}$ ,  $\mathcal{E} = \{(v_i, v_j, v_t) | 1 \le i < j < t \le 7\}$ . Then  $(\{v_1, v_2, v_3, v_4, v_5, v_6\}, \{(v_1, v_2, v_3), (v_3, v_4, v_5), (v_5, v_6, v_1)\})$  is a loose cycle and  $(\{v_1, v_2, v_3, v_4\}, \{(v_1, v_2, v_3), (v_2, v_3, v_4), (v_3, v_4, v_1), (v_4, v_1, v_2)\})$  is a tight cycle (see Figure 1).

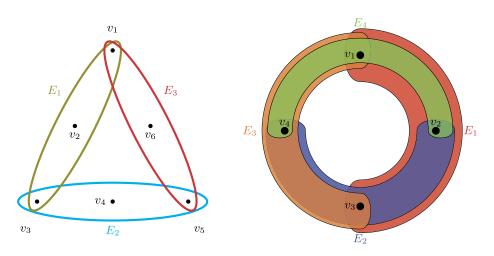


FIG. 1. Left: a loose cycle of three edges  $E_1$ ,  $E_2$ ,  $E_3$ . Right: a tight cycle of four edges  $E_1$ ,  $E_2$ ,  $E_3$ ,  $E_4$ . Both cycles are subgraphs of the 3-uniform hypergraph  $\mathcal{H}_3(\mathcal{V},\mathcal{E})$ .

Next, let us review uniform hypergraphs with a planted partitioning structure, also known as stochastic block model (SBM). For any positive integers n, m, k with m,  $k \ge 2$ , and positive sequences  $0 < q_n < p_n < 1$  (possibly depending on n), let  $\mathcal{H}^k_m(n,p_n,q_n)$  denote a m-uniform hypergraph of n vertices and k balanced communities, in which  $p_n$  ( $q_n$ ) represents the hyperedge probability within (between) communities. More explicitly, any vertex  $i \in [n] \equiv \{1,2,\ldots,n\}$  is assigned, independently and uniformly at random, a label  $\sigma_i \in [k] \equiv \{1,2,\ldots,k\}$ , and then each possible hyperedge ( $i_1,i_2,\ldots,i_m$ ) is included with probability  $p_n$  if  $\sigma_{i_1} = \sigma_{i_2} = \cdots = \sigma_{i_m}$  and with probability  $q_n$  otherwise. In particular,  $\mathcal{H}^2_2(n,p_n,q_n)$  (with m = k = 2) reduces to the ordinary bisection stochastic block models considered by [44, 55].

Let  $A \in \{0,1\}$  m denote the symmetric adjacency tensor of order m associated with  $\mathcal{H}^k_m(n,p_n,q_n)$ . By symmetry, we mean that  $A_{i_1i_2...i_m}=A_{\psi(i_1)\psi(i_2)...\psi(i_m)}$  for any permutation  $\psi$  of  $(i_1,i_2,\ldots,i_m)$ . For convenience, assume  $A_{i_1i_2...i_m}=0$  if  $i_s=i_t$  for some distinct  $s,t\in\{1,2,\ldots,m\}$ , that is, the hypergraph has no self-loops. Conditional on  $\sigma_1,\ldots,\sigma_n$ , the  $A_{i_1i_2...i_m}$ 's, with  $i_1,\ldots,i_m$  pairwise distinct, are assumed to be independent following the distribution below:

(1) 
$$\mathbb{P}(A_{i_1i_2...i_m} = 1 | \sigma) = p_{i_1i_2...i_m}(\sigma), \qquad \mathbb{P}(A_{i_1i_2...i_m} = 0 | \sigma) = q_{i_1i_2...i_m}(\sigma),$$
where  $\sigma = (\sigma_1, \dots, \sigma_n),$ 

$$p_{i_1i_2...i_m}(\sigma) = \begin{cases} p_n & \sigma_{i_1} = \dots = \sigma_{i_m}, \\ q_n & \text{otherwise}, \end{cases} \qquad q_{i_1i_2...i_m}(\sigma) = 1 - p_{i_1i_2...i_m}(\sigma).$$

In other words, each possible hyperedge  $(i_1,\ldots,i_m)$  is included with probability  $p_n$  if the vertices  $i_1,\ldots,i_m$  belong to the same community, and with probability  $q_n$  otherwise. Let  $\mathcal{H}_m(n,\frac{p_n+(k^{m-1}-1)q_n}{k^{m-1}})$  denote the m-uniform hypergraph without community structure, that is, an Erdős-Rényi model in which each possible hyperedge is included with common probability  $\frac{p_n+(k^{m-1}-1)q_n}{k^{m-1}}$ . We consider such a special choice of hyperedge probability in order to make the model have the same average degree as  $\mathcal{H}_m^k(n,p_n,q_n)$ . In particular,  $\mathcal{H}_2(n,\frac{p_n+(k-1)q_n}{k})$  with m=2 becomes the traditional Erdős-Rényi model that has been well studied in ordinary graph literature; see [14, 15, 21, 25, 54]. Nonuniform hypergraphs can be simply viewed as a superposition of uniform ones; see Section 3. Throughout this paper, we assume k and m are fixed constants independent of n.

Given an observed adjacency tensor  $\hat{A}$ , does  $\hat{A}$  represent a hypergraph that exhibits community structure? In the present setting, this problem can be formulated as testing the following hypothesis:

(2) 
$$H_0: A \sim \mathcal{H}_m\left(n, \frac{p_n + (k^{m-1} - 1)q_n}{k^{m-1}}\right) \quad \text{vs.} \quad H_1: A \sim \mathcal{H}_m^k(n, p_n, q_n).$$

When m = k = 2, problem (2) has been well studied in the literature. Specifically, for extremely sparse scenario  $p_n \approx q_n \ll n^{-1}$ , [44] show that  $H_0$  and  $H_1$  are always indistinguishable in the sense that all tests are asymptotically powerless; for bounded degree case  $p_n \approx q_n \approx n^{-1}$ , the two models are distinguishable if and only if the signal-to-noise ratio (SNR) is greater than 1 [44, 45, 55]; for dense scenario  $p_n \approx q_n \gg n^{-1}$ ,  $H_0$  and  $H_1$  are always distinguishable and a number of algorithms have been developed (see [3, 10, 12, 26, 27, 40]). When m = 2 and  $k \geq 3$ , the above statements remain true for extremely sparse and dense scenarios; but for bounded degree scenario, SNR > 1 is only a sufficient condition for successfully distinguishing  $H_0$  from  $H_1$  while a necessary condition remains an open problem (see [3, 11, 56]). Abbe [1] provides a comprehensive review of the recent development in this field. From the best of our knowledge, there is a lack of literature dealing with the testing problem (2) for general m. The literature on hypergraph analysis mainly focused on community detection (see [8, 17, 31, 32, 35, 39, 41, 42, 51]).

1.2. Our contributions. The aim of this paper is to provide a study on hypergraph testing under a spectrum of hyperedge probability scenarios. Our results consist of four major parts. Section 2.1 deals with the extremely sparse scenario  $p_n \approx q_n \ll n^{-m+1}$ , in which we show that  $H_0$  and  $H_1$  are always indistinguishable in the sense of contiguity. Section 2.2 deals with bounded degree case  $p_n \approx q_n \approx n^{-m+1}$ , in which we show that  $H_0$  and  $H_1$  are distinguishable if the SNR of uniform hypergraph is greater than a certain threshold, but indistinguishable if the SNR is below another threshold. Interestingly, when k = 2, the two thresholds are nearly tight in that they are of the same order  $2^{-m}$  (up to universal constants). We also construct a powerful test statistic when SNR is greater than one based on counting the "long loose cycles". Section 2.3 deals with dense scenario  $p_n \simeq q_n \gg n^{-m+1}$ . We propose a test based on counting the hyperedges, l-hypervees, and l-hypertriangles with l determined by the order of  $p_n$  (or  $q_n$ ), and show that the power of the proposed test approaches one as the number of vertices goes to infinity. In Section 3, we extend some of the previous results to nonuniform hypergraph testing. We propose a new test involving both edge and hyperedge information and show that it is generally more powerful than the classic test using edge information only (see Remark 3.1). The results of the present paper can be viewed as nontrivial extensions of the ordinary graph testing results such as [26, 44, 45]. Section 4 provides numerical studies to support our theory. Possible extensions are discussed in Section 5 and proof of the main results are collected in [57].

Figure 2 displays a phase transition phenomenon in the special 3-uniform hypergraph, based on our results in Sections 2.1 and 2.3. We find that  $H_0$  and  $H_1$  are indistinguishable if the hyperedge probabilities satisfy  $p_n$ ,  $q_n = o(n^{-2})$  (see red zone), and are distinguishable if  $p_n$ ,  $q_n \gg n^{-2}$  (see green zone), which is consistent with [6] who showed that community detection with weak consistency is possible if and only if  $p_n$ ,  $q_n \gg n^{-2}$ . Therefore, the seemingly different perspectives, that is, hypothesis testing and community detection, appear to coincide here. In contrast, the spectral algorithm proposed by [32] is able to detect communities with strong consistency if  $p_n$ ,  $q_n \gg n^{-2}(\log n)^2$  (later improved to  $p_n$ ,  $q_n \gg n^{-2}\log n$  by [5, 41]). For bounded degree case  $p_n$ ,  $q_n \approx n^{-2}$ , detection algorithms better than random guess were proposed by [6, 18, 23]. Overall, in the references [6, 18], the SNR conditions are not comparable to our  $\kappa > 1$  since unknown constants are involved in their conditions. The SNR condition in [23] seems more restrictive than our condition  $\kappa > 1$ .

On the next page, Figure 3 demonstrates the distinguishable and indistinguishable regions for two-community graph (left) and two-community 3-uniform hypergraph (right) in the bounded degree regime, that is,  $p_n = \frac{a}{n^{m-1}}$ ,  $q_n = \frac{b}{n^{m-1}}$ . The regions are characterized by (a,b) with a > b > 0. The left plot is based on [44] who derived the decision boundary  $(a-b)^2 = 2(a+b)$ . The right plot is based on our Theorem 2.6 with the decision boundary

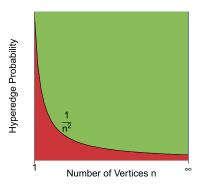


FIG. 2. Phase transition for 3-uniform hypergraph. Red: indistinguishable; green: distinguishable.

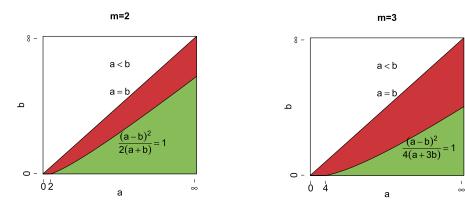


FIG. 3. Phase transition in bounded degree case. Red: indistinguishable; green: distinguishable.

 $(a-b)^2 = 4(a+3b)$ . It can be observed that m=3 yields a larger indistinguishable region than m=2, which reveals a substantial difference for hypothesis testing in the two models.

**2. Main results.** In this section, we present our main results in three parts, organized by the sparsity of the network. The contiguity theory for the extremely sparse case is presented in Section 2.1, followed by the contiguity and orthogonality result for the bounded degree case in Section 2.2. In Section 2.3, we construct a powerful test by counting the hyperedges, l-hypervees, and l-hypertriangles for the dense case. Throughout this paper, we assume k and m are fixed positive integers.

2.1. A contiguity theory for extremely sparse case. In this section, we consider the testing problem (2) with  $p_n \approx q_n \ll n^{-m+1}$ , that is, the hyperedge probability of the hypergraph is extremely low. For technical convenience, we only consider  $p_n = \frac{a}{n^{\alpha}}$  and  $q_n = \frac{b}{n^{\alpha}}$  with constants a > b > 0 and  $\alpha > m - 1$ . The results in this section may be extended to general orders of  $p_n$  and  $q_n$  with more cumbersome arguments. We will show that no test can successfully distinguish  $H_0$  from  $H_1$  in such a situation. The proof proceeds by showing that the probability measures associated with  $H_0$  and  $H_1$  are contiguous (see Theorem 2.1). We remark that contiguity has also been used to prove indistinguishability for ordinary graphs (see [44, 45]).

Let  $\mathbb{P}_n$  and  $\mathbb{Q}_n$  be sequences of probability measures on a common probability space  $(\Omega_n, \mathcal{F}_n)$ . We say that  $\mathbb{P}_n$  and  $\mathbb{Q}_n$  are mutually *contiguous* if for every sequence of measurable sets  $A_n \subset \Omega_n$ ,  $\mathbb{P}_n(A_n) \to 0$  if and only if  $\mathbb{Q}_n(A_n) \to 0$  as  $n \to \infty$ . They are said to be *orthogonal* if there exists a sequence of measurable sets  $A_n$  such that  $\mathbb{P}_n(A_n) \to 0$  and  $\mathbb{Q}_n(A_n) \to 1$  as  $n \to \infty$ . According to [44], two probability models are indistinguishable if their associated probability measures are mutually contiguous, and two probability models are distinguishable if their associated probability measures are orthogonal. The following theorem shows that  $H_0$  and  $H_1$  are indistinguishable.

THEOREM 2.1. If  $\alpha > m-1$  and a > b > 0 are fixed constants, then the probability measures associated with  $H_0$  and  $H_1$  are mutually contiguous.

The proof of Theorem 2.1 proceeds by showing that the ratio of the likelihood function of  $H_1$  over  $H_0$  converges in distribution to 1 under  $H_0$ , which implies the contiguity of  $H_1$  and  $H_0$  [36]. Theorem 2.1 says that the hypergraphs in  $H_0$  and  $H_1$  are indistinguishable, and hence, no test can successfully separate the two hypotheses. One intuitive explanation is that

when  $\alpha > m-1$ , the average degree of both hypergraph models converges to zero. To see this, the average degree is

(3) 
$$\binom{n}{m-1} \frac{a + (k^{m-1} - 1)b}{k^{m-1}n^{\alpha}},$$

which goes to zero as  $n \to \infty$  if  $\alpha > m-1$ . Therefore, the signals in both models are not strong enough to support a successful test. It is easy to see that the average degree becomes bounded when  $\alpha = m-1$  which will be investigated in the next section.

2.2. Bounded degree case. In this section, we consider  $p_n \times q_n \times n^{-m+1}$  which leads to bounded average degrees for the models in  $H_0$  and  $H_1$ ; see (3). For convenience, let us denote  $p_n = \frac{a}{n^{m-1}}$  and  $q_n = \frac{b}{n^{m-1}}$  for fixed a > b > 0. Define the signal to noise ratio (SNR) for  $H_0$  and  $H_1$  as

(4) 
$$\kappa = \frac{(a-b)^2}{k^{m-1}(m-2)![a+(k^{m-1}-1)b]}.$$

When m=k=2, it is easy to check that  $\kappa=\frac{(a-b)^2}{2(a+b)}$  which becomes the classic SNR of ordinary stochastic block models considered by [2, 3, 44]. Hence, it is reasonable to view  $\kappa$  defined in (4) as a generalization of the classic SNR to the hypergraph model  $\mathcal{H}_m^k(n,\frac{a}{n^{m-1}},\frac{b}{n^{m-1}})$ . Like the classic SNR, the value of  $\kappa$  characterizes the separability between communities. Intuitively, when  $\kappa$  is large which means that the communities are very different, the testing problem (2) becomes simpler. The following result showes that when  $\kappa>1$ , successful testing becomes possible.

THEOREM 2.2. Suppose that a > b > 0 are fixed constants,  $m, k \ge 2$ . If  $\kappa > 1$ , then the probability measures associated with  $H_0$  and  $H_1$  are orthogonal.

We prove Theorem 2.2 by constructing a sequence of events dependent on the number of long loose cycles and showing that the probabilities of the events converge to 1 (or 0) under  $H_0$  (or  $H_1$ ), based on the high moments driven asymptotic normality theorem from Gao and Wormald [29]. Theorem 2.2 says that it is possible to distinguish the hypotheses  $H_0$  and  $H_1$  provided that  $\kappa > 1$ . Abbe and Sandon [3] obtained relevant results in the ordinary graph setting, that is, m = 2 and  $k \ge 2$  in our case; see Corollary 2.8 therein which states that community detection in polynomial time becomes possible if SNR > 1. Whereas Theorem 2.2 holds for arbitrary  $m, k \ge 2$ . Hence, our result can be viewed as an extension of [3] to hypergraph setting.

Let us now propose a test statistic based on "long loose cycles" that can successfully distinguish  $H_0$  and  $H_1$  when  $\kappa > 1$ . Let  $\xi_n$  be a positive integer sequence diverging along with n. Let  $X_{\xi_n}$  be the number of loose cycles, each consisting of exactly  $\xi_n$  edges. Define

$$\mu_{n0} = \frac{\lambda_m^{\xi_n}}{2\xi_n}, \qquad \mu_{n1} = \mu_{n0} + \frac{k-1}{2\xi_n} \left[ \frac{a-b}{k^{m-1}(m-2)!} \right]^{\xi_n},$$

where  $\lambda_m = \frac{a + (k^{m-1} - 1)b}{k^{m-1}(m-2)!}$  for any  $m \ge 2$ . Note that when m = 2,  $\lambda_m = \frac{a + (k-1)b}{k}$  is the average degree [11]. Let  $\mathbb{P}_{H_1}$  denote the probability measure induced by A under  $H_1$ . We have the following theorem about the asymptotic property of  $X_{\xi_n}$ .

THEOREM 2.3. Suppose  $\kappa > 1$  and  $1 \ll \xi_n \leq \delta_0 \log_{\lambda_m} \log_{\gamma} n$ , where  $\gamma > 1$  and  $0 < \delta_0 < 2$  are constants. Then, under  $H_l$  for l = 0, 1,  $\frac{X_{\xi_n - \mu_{nl}}}{\sqrt{\mu_{nl}}} \stackrel{d}{\to} N(0, 1)$  as  $n \to \infty$ . Furthermore, for any constant C > 0,  $\mathbb{P}_{H_1}(|\frac{X_{\xi_n - \mu_{n0}}}{\sqrt{\mu_{n0}}}| > C) \to 1$  as  $n \to \infty$ .

Table 1					
$Minimal\ n$	to achieve	a desirable	value	of $\xi_n$	

Desirable $\xi_n$	3	4	5	6
Minimal n	2	3	25	29,786

The proof is based on the asymptotic normality theory developed by [29]. According to Theorem 2.3, we propose the following test statistic:

$$T_{\xi_n} = \frac{X_{\xi_n} - \mu_{n0}}{\sqrt{\mu_{n0}}}.$$

We remark that computation of  $T_{\xi_n}$  is typically in super-polynomial time since it requires to find  $X_{\xi_n}$  which has complexity  $n^{O(\xi_n)}$ . By Theorem 2.3,  $T_{\xi_n} \stackrel{d}{\to} N(0, 1)$  under  $H_0$ . Hence, we construct the following testing rule at significance level  $\alpha \in (0, 1)$ :

reject 
$$H_0$$
 if and only if  $|T_{\xi_n}| > z_{\alpha/2}$ ,

where  $z_{\alpha/2}$  is the  $(1 - \alpha/2)$ -quantile of N(0, 1). It follows by Theorem 2.3 that  $\mathbb{P}_{H_1}(|T_{\xi_n}| > z_{\alpha/2}) \to 1$ , that is, the power of  $T_{\xi_n}$  approaches one when  $\kappa > 1$ .

Theorem 2.3 requires  $\xi_n \to \infty$  and to grow slower than an iterative logarithmic order. This is due to the use of [29] which requires  $\xi_n$  to diverge with  $\xi_n \lambda_m^{\xi_n} = o(\log n)$ . In practice, we suggest choosing  $\xi_n = \lfloor \delta_0 \log_{\lambda_m} \log_{\gamma} n \rfloor$  with  $\gamma$  close to 1 and  $\delta_0$  close to 2. Such  $\gamma$  and  $\delta_0$  will make  $\xi_n$  suitably large so that the test statistic  $T_{\xi_n}$  becomes valid. For instance, Table 1 demonstrates the values of  $\xi_n$  along with n with  $\delta_0 = 1.99$ ,  $\gamma = 1.01$ ,  $\lambda_m = 10$ . We can see that, for a moderate range of n, the values of  $\xi_n$  are sufficiently large to make the test valid. When  $\xi_n = l$  is fixed and the exact  $\alpha$ -level test is needed, we should use Poisson distribution as the null limiting distribution. In this case, the number of l-loose cycle  $X_l$  converges in distribution to Poisson distribution with mean  $\mu_0 = \frac{\lambda_m^l}{2l}$  under  $H_0$  (It's implied by the proof of Theorem 2.5). It should be mentioned that the calculation of  $T_{\xi_n}$  requires known values of a and b. When a and b are unknown, motivated by the ordinary graph [44], they can be estimated as follows. Define

$$\widehat{\lambda}_m = \frac{n^{m-1}|\mathcal{E}|}{(m-2)!\binom{n}{m}}, \qquad \widehat{f} = \left(2\xi_n X_{\xi_n} - \widehat{\lambda}_m^{\xi_n}\right)^{\frac{1}{\xi_n}},$$

where  $|\mathcal{E}|$  is the number of observed hyperedges and  $X_{\xi_n}$  is the number of loose cycles of length  $\xi_n$ . Let  $\widehat{a}_n = (m-2)![\widehat{\lambda}_m + (k^{m-1}-1)(k-1)^{-\frac{1}{\xi_n}}\widehat{f}]$  and  $\widehat{b}_n = (m-2)![\widehat{\lambda}_m - (k-1)^{-\frac{1}{\xi_n}}\widehat{f}]$ . The following theorem says that  $\widehat{a}_n$  and  $\widehat{b}_n$  are consistent estimators of a and b, respectively.

THEOREM 2.4. Suppose  $\kappa > 1$  and  $\xi_n$  satisfies the condition in Theorem 2.3. Then  $\widehat{a}_n \to a$  and  $\widehat{b}_n \to b$  in probability.

Another interesting question is to investigate for what values of  $\kappa$  a successful test becomes impossible. When m=k=2, [44] showed that no test can successfully distinguish  $H_0$  from  $H_1$  provided  $\kappa < 1$ ; and a successful test becomes possible provided  $\kappa > 1$ . It is substantially challenging to obtain such a sharp result when k becomes larger. For instance, in the ordinary graph setting, [46] obtained a (nonsharp) condition in terms of SNR when  $k \geq 3$  under which successful test becomes impossible. In Theorem 2.5 below, we address a similar question in the hypergraph setting. For any integers  $m \geq 3$ ,  $k \geq 2$ , define

 $au_1(m,k) = {m \choose 2}^{-1} \sum_{i=1}^{\lceil \frac{m}{2}-1 \rceil} \frac{1}{k^{2i-1}} {m \choose i+2}$  and  $au_2(m,k) = 1 + {m \choose 2}^{-1} \sum_{i=1}^{m-2} \frac{1}{k^{2i}} {m \choose i+2}$ . The quantities  $au_1(m,k)$  and  $au_2(m,k)$  will jointly characterize a spectrum of  $(m,k,\kappa)$  such that successful test does not exist.

THEOREM 2.5. Suppose that  $m \ge 3$ ,  $k \ge 2$  are integers satisfying  $\tau_1(m, k) \le 1$ , a > b > 0 are fixed constants and  $\alpha = m - 1$ . If

(5) 
$$0 < \kappa < \frac{1}{\tau_2(m,k)(k^2 - 1)},$$

then the probability measures associated with  $H_0$  and  $H_1$  are mutually contiguous.

The proof of Theorem 2.5 relies on Janson's contiguity theory [36]. Theorem 2.5 says that when  $\tau_1(m,k) \le 1$  and  $\kappa$  falls in the range (5), there is no test that can successfully distinguish the hypotheses  $H_0$  and  $H_1$ . It should be emphasized that the condition  $\tau_1(m,k) \le 1$  holds for a broad range of pairs (m,k). For instance, such condition holds for any  $k \ge 2$  and  $3 \le m \le 6$ . To see this, for any  $k \ge 2$ ,  $\tau_1(3,k) = \frac{1}{3k} < 1$ ,  $\tau_1(4,k) = \frac{2}{3k} < 1$ ,  $\tau_1(5,k) = \frac{1}{k} + \frac{1}{2k^3} < 1$  and  $\tau_1(6,k) = \frac{4}{3k} + \frac{1}{k^3} < 1$ . Note that  $m \le 6$  covers most of the practical cases (see [32]).

Combining Theorems 2.5 and 2.2, it is still unknown whether  $H_0$  and  $H_1$  are distinguishable when  $\frac{1}{\tau_2(m,k)(k^2-1)} \le \kappa \le 1$ . Such result can be further improved for the special case k=2, and we close the gap if in addition m=3, as presented in the following theorem.

THEOREM 2.6. For k = 2, the following results hold.

- 1. For any  $m \ge 2$ , if  $0 < \kappa < 2^{2-m}$ , then  $H_0$  and  $H_1$  are indistinguishable. Moreover, for any given constant  $\kappa_0$  such that  $\kappa_0 > \frac{m(m-1)\log 2}{2^{m-1}-1}$ , there exist a > b > 0 such that the SNR  $\kappa$  for the hypotheses  $H_0$  and  $H_1$  is equal to  $\kappa_0$ , and  $H_0$  and  $H_1$  are distinguishable by the likelihood ratio test.
- 2. For any  $m \ge 2$ , if  $0 < \kappa < \frac{m(m-1)}{2N_m}$ , where  $N_m = [3^m + (-1)^m]/4 2^{m-1} + 1/2$ , then  $H_0$  and  $H_1$  are indistinguishable.

Specifically, Part 1 indicates that, when SNR is below  $2^{2-m}$ ,  $H_0$  and  $H_1$  are indistinguishable; while they are possible to be distinguishable when SNR is greater than  $\frac{m(m-1)\log 2}{2^{m-1}-1}$ . Essentially, Part 1 implies that the derived SNR upper and lower bounds satisfy the following relationship:

$$0 < \sup_{m \ge 1} \frac{1}{m^2} \cdot \frac{\text{SNR upper bound}}{\text{SNR lower bound}} < \infty,$$

and

$$0 < \min_{m > 1} \frac{\text{SNR lower bound}}{2^{-m}} \le \max_{m > 1} \frac{\text{SNR lower bound}}{2^{-m}} < \infty.$$

Part 2 in Theorem 2.6 provides an SNR interval for  $H_1$  and  $H_0$  to be indistinguishable. When m=3,  $N_3=3$  leads to an SNR interval  $0<\kappa<1$  which is sharp since  $\kappa>1$  implies that  $H_0$  and  $H_1$  are distinguishable thanks to Theorem 2.2. For k=2 and general m, the upper bound  $\frac{m(m-1)}{2N_m}$  may be less sharp as m grows. In particular, when m is large, the upper bound is of order  $m^2 3^{-3}$ , which can actually be improved as shown in Part 1 of Theorem 2.6. Specifically, Part 1 indicates that, when SNR is below  $2^{2-m}$ ,  $H_0$  and  $H_1$  are indistinguishable; while they are possible to be distinguishable when SNR is greater than  $m^2 2^{-m}$  up to a constant in the special case k=2. Note that for  $3\leq m\leq 8$ ,  $\frac{m(m-1)}{2N_m}>2^{2-m}$  and for  $m\geq 9$ ,  $\frac{m(m-1)}{2N_m}<2^{2-m}$ .

The proof of Theorem 2.6 relies on a truncation technique to show the stochastic boundedness of the likelihood ratio and a delicate derivation of a lower bound for the truncated likelihood ratio. An interesting consequence of Part 1 is that the likelihood ratio test is possible to distinguish  $H_0$  and  $H_1$  even when  $\kappa$  is below 1 (but greater than  $\frac{m(m-1)\log 2}{2^{m-1}-1}$ ). However, the computation of the likelihood ratio is NP-hard. When  $\kappa > 1$ , the l-cycle based test can distinguish  $H_0$  and  $H_1$  as well (see Theorem 2.3), and is computationally less expensive.

REMARK 2.1. We provide more details about why truncation technique is needed in our setting. The proof of Theorem 2.6 relies on the first moment technique which requires the analysis of  $\mathbb{E}_1 Y_n$  where  $\mathbb{E}_1$  is the expectation taken under  $H_1$  and  $Y_n = \frac{dP_1}{dP_0}$  is the likelihood ratio of  $H_1$  to  $H_0$ . We find that the expression of  $\mathbb{E}_1 Y_n$  includes terms like

(6) 
$$\mathbb{E}_{\sigma} \exp \left( \sum_{i_1 < \dots < i_m} \operatorname{poly}(\sigma_{i_1}, \dots, \sigma_{i_m}) \right),$$

where poly( $\sigma_{i_1}, \ldots, \sigma_{i_m}$ ) is an *m*th-order polynomial of  $\sigma_{i_1}, \ldots, \sigma_{i_m} \in \{\pm 1\}$ . When m = 2, (6) becomes a second-order polynomial which is asymptotically  $\chi^2$  by CLT. And so, (6) is heuristically  $\mathbb{E} \exp(\text{const} \times \chi^2)$  which is finite. This is why no truncation technique is needed here

However, when m = 3, the above polynomial is third-order which is asymptotically  $Z^3$  where  $Z \sim N(0, 1)$ . And as a result, (6) is heuristically  $\mathbb{E}\exp(\operatorname{const} \times Z^3)$  which is infinite. This is why we used the truncation technique, that is, to truncate the likelihood ratio on an even with high probability so that the higher-order polynomials are well controlled, and the truncated likelihood ratio has a finite expectation.

2.3. A powerful test for dense uniform hypergraph. In this section, we consider the problem of testing community structure in dense m-uniform hypergraphs with  $p_n \approx q_n \gg n^{-m+1}$ . Our approach is based on counting the hyperedges, l-hypervees, and l-hypertriangles in the observed hypergraph. To ensure the success of our test, l needs to be properly selected according to the hyperedge probability of the model. Under such correct selection, we derive asymptotic normality for the test and analyze its power. We also discuss the effect of misspecified l in Remark 2.2. Our method can be viewed as a generalization of [26, 27] from ordinary graph testing. The different features of the hypergraph cycles make our generalization nontrivial.

For convenience, let us denote  $p_n = \frac{a_n}{n^{m-1}}$  and  $q_n = \frac{b_n}{n^{m-1}}$  with diverging  $a_n$ ,  $b_n$ . Therefore, (2) becomes the following hypothesis testing problem:

(7) 
$$H'_0: A \sim \mathcal{H}_m\left(n, \frac{a_n + (k^{m-1} - 1)b_n}{k^{m-1}n^{m-1}}\right)$$
 vs.  $H'_1: A \sim \mathcal{H}_m^k\left(n, \frac{a_n}{n^{m-1}}, \frac{b_n}{n^{m-1}}\right)$ .

We temporarily assume that there exists an integer  $1 \le l \le \frac{m}{2}$  such that  $n^{l-1} \ll a_n \times b_n \ll n^{l-\frac{2}{3}}$ . Such a requirement will be relaxed by invoking a sparsification technique. Note that model (7) allows  $1 \ll a_n \times b_n \ll n^{1/3}$  (with l=1), compared with spectral algorithm [32] which requires  $a_n \gg (\log n)^2$  or  $a_n \gg \log n$  in [41].

We consider the following degree-corrected SBM in [19, 20, 26] which is more general than (1) and generalizes its counterpart in ordinary graphs. Let  $\{W_i, i = 1, ..., n\}$  be nonnegative i.i.d. random variables with  $\mathbb{E}(W_1^2) = 1$  and  $\{\sigma_i, i = 1, ..., n\}$  be i.i.d. random variables from multinomial distribution  $\mathrm{Mult}(k, 1, 1/k)$ . Assume that  $W_i$ 's and  $\sigma_i$ 's are independent.

Given  $W_i$ 's and  $\sigma_i$ 's, the  $A_{i_1i_2...i_m}$ 's, with pairwise distinct  $i_1, ..., i_m$ , are conditional independent satisfying

(8) 
$$\mathbb{P}(A_{i_1 i_2 \dots i_m} = 1 | W, \sigma) = W_{i_1} \dots W_{i_m} p_{i_1 i_2 \dots i_m}(\sigma),$$

$$\mathbb{P}(A_{i_1 i_2 \dots i_m} = 0 | W, \sigma) = 1 - W_{i_1} \dots W_{i_m} p_{i_1 i_2 \dots i_m}(\sigma),$$

where  $W = (W_1, ..., W_n)$ ,

$$p_{i_1 i_2 \dots i_m}(\sigma) = \begin{cases} \frac{a_n}{n^{m-1}} & \sigma_{i_1} = \dots = \sigma_{i_m}, \\ \frac{b_n}{n^{m-1}} & \text{otherwise.} \end{cases}$$

We call (8) the degree-corrected SBM in hypergraph setting. The degree-correction weights  $W_i$ 's can capture the degree of inhomogeneity exhibited in many social networks. When m=2, (8) reduces to the classical degree-corrected SBM for ordinary graphs (see [19, 20, 26]). For ordinary graphs, [26] proposed a test through counting small subgraphs to distinguish the degree-corrected SBM from an Erdős–Rényi model. In what follows, we generalize their results to hypergraphs through counting small sub-hypergraphs, including hyperedges, l-hypervee, and l-hypertriangles, with definitions given below.

DEFINITION 2.1. An l-hypervee consists of two hyperedges with l common vertices. An l-hypertriangle is an l-cycle consisting of three hyperedges.

For example, in Figure 4, the hyperedge set  $\{(v_1, v_2, v_3, v_4), (v_3, v_4, v_5, v_6)\}$  is a 2-hypervee, and  $\{(v_1, v_2, v_3, v_4), (v_3, v_4, v_5, v_6), (v_5, v_6, v_1, v_2)\}$  is a 2-hypertriangle.

Consider the following probabilities of hyperedge, hypervee and hypertriangle in  $\mathcal{H}_m^k(n, \frac{a_n}{n^{m-1}}, \frac{a_n}{n^{m-1}})$ :

$$\begin{split} E &= \mathbb{P}(A_{i_1 i_2 \dots i_m} = 1), \\ V &= \mathbb{P}(A_{i_1 i_2 \dots i_m} A_{i_{m-l+1} \dots i_{2m-l}} = 1), \\ T &= \mathbb{P}(A_{i_1 i_2 \dots i_m} A_{i_{m-l+1} \dots i_{2m-l}} A_{i_{2m-2l+1} \dots i_{3(m-l)} i_1 \dots i_l} = 1). \end{split}$$

It follows from direct calculations that

$$E = (\mathbb{E}W_1)^m \frac{a_n + (k^{m-1} - 1)b_n}{n^{m-1}k^{m-1}},$$

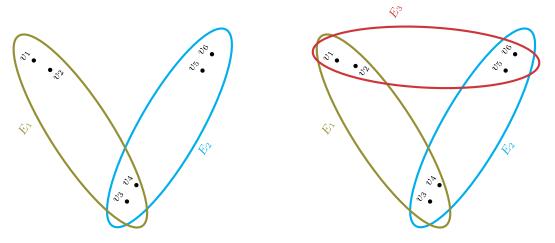


FIG. 4. Examples of hypervee (left) and hypertriangle (right) with two common vertices between consecutive hyperedges.

$$V = (\mathbb{E}W_1)^{2(m-l)} \left( \frac{(a_n - b_n)^2}{n^{2(m-l)} k^{2m-l-1}} + \frac{2(a_n - b_n)b_n}{n^{2(m-1)} k^{m-1}} + \frac{b_n^2}{n^{2(m-1)}} \right),$$

$$T = (\mathbb{E}W_1)^{3(m-2l)} \left( \frac{(a_n - b_n)^3}{n^{3(m-1)} k^{3(m-l)-1}} + \frac{3(a_n - b_n)^2 b_n}{n^{3(m-1)} k^{2m-l-1}} + \frac{3(a_n - b_n)b_n^2}{n^{3(m-1)} k^{m-1}} + \frac{b_n^3}{n^{3(m-1)}} \right).$$

Define  $\mathcal{T} = T - (\frac{V}{E})^3$ . The following result demonstrates a strong relationship between  $\mathcal{T}$  and  $H'_0, H'_1$ .

PROPOSITION 2.7. Under  $H'_0$ ,  $\mathcal{T} = 0$  and under  $H'_1$ ,  $\mathcal{T} \neq 0$ .

Proposition 2.7 says that  $H'_0$  holds if and only if  $\mathcal{T} = 0$ . Hence, it is reasonable to use an empirical version of  $\mathcal{T}$ , namely,  $\widehat{\mathcal{T}}$ , as a test statistic for (7).

Prior to constructing  $\widehat{\mathcal{T}}$ , let us introduce some notation. For convenience, we use  $i_1:i_m$  to represent the ordering  $i_1i_2...i_m$ . Also define  $C_{2m-l}(A)$  and  $C_{3(m-l)}(A)$  for any adjacency tensor A as follows.

$$\begin{split} C_{2m-l}(A) &= A_{i_1:i_m} A_{i_{m-l+1}:i_{2m-l}} + A_{i_2:i_{m+1}} A_{i_{m-l+2}:i_{2m-l}i_1} + \dots + A_{i_{2m-l}i_1:i_{m-1}} A_{i_{m-l}:i_{2m-l-1}}, \\ C_{3(m-l)}(A) &= A_{i_1:i_m} A_{i_{m-l+1}:i_{2m-l}} A_{i_{2m-2l+1}:i_{3(m-l)}i_1:i_l} \\ &\quad + A_{i_2:i_{m+1}} A_{i_{m-l+2}:i_{2m-l+1}} A_{i_{2m-2l+2}:i_{3(m-l)}i_1:i_{l+1}} \\ &\quad + \dots + A_{i_{m-l}:i_{2m-l-1}} A_{i_{2(m-l)}:i_{3(m-l)}i_1:i_{l-1}} A_{i_{3(m-l)}i_1:i_{m-1}}. \end{split}$$

Note that  $C_{2m-l}(A)$  is the number of hypervees in the given vertex ordering  $i_1i_2...i_{2m-l}$ , while  $C_{3(m-l)}(A)$  counts the number of hypertriangles in the given vertex ordering  $i_1i_2...i_{3(m-l)}$ . Define  $\widehat{E}$ ,  $\widehat{V}$ ,  $\widehat{T}$  as the empirical versions of E, V, T:

(9) 
$$\widehat{E} = \frac{1}{\binom{n}{m}} \sum_{i \in c(m,n)} A_{i_1:i_m},$$

$$\widehat{V} = \frac{1}{\binom{n}{2m-l}} \sum_{i \in c(2m-l,n)} \frac{C_{2m-l}(A)}{2m-l},$$

$$\widehat{T} = \frac{1}{\binom{n}{3(m-l)}} \sum_{i \in c(3(m-l),n)} \frac{C_{3(m-l)}(A)}{m-1},$$

where, for any positive integers s, t,  $c(s,t) = \{(i_1, \dots, i_s) : 1 \le i_1 < \dots < i_s \le t\}$ . We have the following asymptotic normality result.

THEOREM 2.8. Suppose  $\mathbb{E}W_1^4 = O(1)$  and  $n^{l-1} \ll a_n \asymp b_n \ll n^{l-\frac{2}{3}}$  for some integer  $1 \le l \le \frac{m}{2}$ . Moreover, let

(10) 
$$\delta := \frac{\sqrt{\binom{n}{3(m-l)}(m-l)}}{\sqrt{T}} \left[ T - \left(\frac{V}{E}\right)^3 \right] \in [0, \infty).$$

Then we have, as  $n \to \infty$ ,

(11) 
$$\frac{\sqrt{\binom{n}{3(m-l)}(m-l)}[\widehat{T}-(\frac{\widehat{V}}{\widehat{E}})^3]}{\sqrt{\widehat{T}}}-\delta \stackrel{d}{\to} N(0,1),$$

(12) 
$$2\sqrt{\binom{n}{3(m-l)}(m-l)}\left[\sqrt{\widehat{T}} - \left(\frac{\widehat{V}}{\widehat{E}}\right)^{\frac{3}{2}}\right] - \delta \stackrel{d}{\to} N(0,1).$$

When l = 1 and m = 2, Theorem 2.8 becomes Theorem 2.2 of [26]. Following (11) in Theorem 2.8, we can construct a test statistic for (7) as

(13) 
$$\widehat{\mathcal{T}}_m = \frac{\sqrt{\binom{n}{3(m-l)}(m-l)}[\widehat{T} - (\frac{\widehat{V}}{\widehat{E}})^3]}{\sqrt{\widehat{T}}}.$$

In practice,  $\widehat{T}$  might be close to zero which may cause computational instability, an alternative test can be constructed based on (12) as

(14) 
$$\widehat{T}'_{m} = 2\sqrt{\binom{n}{3(m-l)}(m-l)} \left[\sqrt{\widehat{T}} - \left(\frac{\widehat{V}}{\widehat{E}}\right)^{\frac{3}{2}}\right].$$

We remark that computation of  $\widehat{\mathcal{T}}_m$  and  $\widehat{\mathcal{T}}_m'$  is in polynomial time since the computations of  $\widehat{T}$ ,  $\widehat{V}$ , and  $\widehat{E}$  all have complexity  $O(n^{3(m-l)})$ . Theorem 2.8 proves asymptotic normality for  $\widehat{\mathcal{T}}_m$  and  $\widehat{\mathcal{T}}_m'$  under both  $H_0'$  and  $H_1'$ . Under  $H_0'$ , that is,  $\delta=0$ , both  $\widehat{\mathcal{T}}_m$  and  $\widehat{\mathcal{T}}_m'$  are asymptotically standard normal. Under  $H_1'$ , both  $\widehat{\mathcal{T}}_m$  and  $\widehat{\mathcal{T}}_m'$  are asymptotically normal with mean  $\delta>0$  and unit variance. When  $\widehat{T}$  has a large magnitude, both test statistics can be used to construct valid rejection regions.

The following Theorem 2.9 says that the power of our test tends to one if  $\delta$  goes to infinity.

THEOREM 2.9. Suppose  $\mathbb{E}W_1^4 = O(1)$  and  $n^{l-1} \ll a_n \asymp b_n \ll n^{l-\frac{2}{3}}$  for some integer  $1 \leq l \leq \frac{m}{2}$ . Under  $H'_1$ , as  $n, \delta \to \infty$ ,  $\mathbb{P}(|\widehat{\mathcal{T}}_m| > z_{\alpha/2}) \to 1$ . The same result holds for  $\widehat{\mathcal{T}}'_m$ .

REMARK 2.2. When there are multiple possible choices for l, Theorem 2.8 and Theorem 2.9 may fail if l is misspecified. For example, if m=4 and the "correct" value is  $l_0=2$  (corresponding to the true hyperedge probability), but we count 1-cycle. Then under  $H_0$ , the test statistic in (11) or (12) is of order  $O_p(n^{\frac{3}{2}})$ , that is, the limiting distribution does not exist. Whereas, if the correct value is  $l_0=1$  but we count 2-cycle, then the test statistic in (11) or (12) have the same limiting distribution (if it exists) under  $H_0$  and  $H_1$ , that is, the power of the test does not approach one. In practice, we recommend using the hyperedge proportion to get a rough estimate for l.

Theorem 2.8 and Theorem 2.9 work for relatively sparse hypergraphs. For denser hypergraphs, we propose a sparsification procedure so that Theorem 2.8 and Theorem 2.9 are valid. For any index  $i_1 < i_2 < \cdots < i_m$ , generate  $\epsilon_{i_1 i_2 \dots i_m} \stackrel{\text{iid}}{\sim} \text{Bernoulli}(r_n)$ . Consider a new hypergraph with adjacency tensor  $\tilde{A}$  defined by  $\tilde{A}_{i_1 i_2 \dots i_m} = \epsilon_{i_1 i_2 \dots i_m} A_{i_1 i_2 \dots i_m}$ , where  $A_{i_1 i_2 \dots i_m}$  are the elements of the original observed adjacency tensor. Under  $H'_0$ , we have

$$\mathbb{E}[\tilde{A}_{i_1 i_2 \dots i_m}] = (\mathbb{E}W_1)^m \frac{(r_n a_n) + (k^{m-1} - 1)(r_n b_n)}{k^{m-1} n^{m-1}}.$$

Set  $\tilde{a}_n = r_n a_n$  and  $\tilde{b}_n = r_n b_n$ . For dense hypergraphs, we could replace A,  $a_n$  and  $b_n$  in (7) by  $\tilde{A}$ ,  $\tilde{a}_n$  and  $\tilde{b}_n$  respectively. Note that the hypergraphs  $\tilde{A}$  and A have the same global community structure. A properly selected  $r_n$  will make Theorem 2.8 and Theorem 2.9 valid.

COROLLARY 2.10. Suppose  $\mathbb{E}W_1^4 = O(1)$  and  $1 \ll a_n \asymp b_n \leq n^{m-1}$ . If  $r_n = o(1)$  and  $n^{l-1} \ll r_n a_n \asymp r_n b_n \ll n^{l-\frac{2}{3}}$  for some integer  $1 \leq l \leq \frac{m}{2}$ . Then the results of Theorems 2.8 and 2.9 based on l-cycle continue to hold based on the sparsified hypergraph  $\tilde{A}$ .

Note that Corollary 2.10 is valid for a broad range of hyperedge probabilities  $\frac{1}{n^{m-1}} \ll p_n \asymp q_n \le 1$ . Since  $H_0$  and  $H_1$  are indistinguishable when  $p_n \asymp q_n \ll \frac{1}{n^{m-1}}$  (see Section 2.1), it covers all density regimes of interest. One just needs to select the sparsification factor  $r_n$  to ensure that  $r_n a_n$  and  $r_n b_n$  fall into the range  $n^{l-1} \ll r_n a_n \asymp r_n b_n \ll n^{l-\frac{2}{3}}$ , provided that one wants to use l-cycles to construct the test. The selection of l has been discussed in Remark 2.2.

REMARK 2.3. In some literature, the degree correction variable  $W_i$  in (8) are assumed to be deterministic [28, 37, 38]. In this case, Theorem 2.8 still holds under mild conditions and the proof goes through with slight modifications. To illustrate this, we consider m = 3. Let  $W = (W_1, ..., W_n)$  be a given and deterministic degree correction vector and denote  $\|W\|_t^t = \sum_{i=1}^n W_i^t$  for positive integer t. Let  $\widehat{T}_1$ ,  $\widehat{E}_1$ ,  $\widehat{V}_1$  be defined as

$$\begin{split} \widehat{T}_1 &= \frac{\sum_{i_1, \dots, i_6: \text{distinct }} A_{i_1 i_2 i_3} A_{i_3 i_4 i_5} A_{i_5 i_6 i_1}}{n^6}, \\ \widehat{V}_1 &= \frac{\sum_{i_1, \dots, i_5: \text{distinct }} A_{i_1 i_2 i_3} A_{i_3 i_4 i_5}}{n^5}, \\ \widehat{E}_1 &= \frac{\sum_{i_1, i_2, i_3: \text{distinct }} A_{i_1 i_2 i_3}}{n^3}. \end{split}$$

Then we have the following result.

PROPOSITION 2.11. Suppose  $1 \ll \|W\|_t^t = O(\|W\|_1)$  for  $2 \le t \le 12$ ,  $\|W\|_1 \asymp \|W\|_2^2 = O(n)$ ,  $p_0 \|W\|_1^2 \gg 1$  and  $p_0^2 \|W\|_1^3 = o(1)$ . Then under  $H_0'$  we have

(15) 
$$\widehat{\mathcal{T}}_3 = \sqrt{\frac{n^6}{\widehat{T}_1}} \left[ \widehat{T}_1 - \left( \frac{\widehat{V}_1}{\widehat{E}_1} \right)^3 \right] \stackrel{d}{\to} N(0, 1).$$

Further, if  $1 \ll a_n \asymp b_n \ll n^{\frac{1}{3}}$ , then the power of the test  $\widehat{\mathcal{T}}_3$  goes to 1 as  $\delta_1 \to \infty$ , where

$$\begin{split} \delta_1 &:= \sqrt{\frac{n^6}{T_1}} \bigg[ T_1 - \left(\frac{V_1}{E_1}\right)^3 \bigg], \\ E_1 &= \frac{a_n + (k^2 - 1)b_n}{n^2 k^2} \frac{\|W\|_1^3}{n^3}, \\ V_1 &= \left(\frac{(a_n - b_n)^2}{n^4 k^4} + \frac{2(a_n - b_n)b_n}{n^4 k^2} + \frac{b_n^2}{n^4}\right) \frac{\|W\|_2^2 \|W\|_1^4}{n^5}, \\ T_1 &= \left(\frac{(a_n - b_n)^3}{n^6 k^5} + \frac{3(a_n - b_n)^2 b_n}{n^6 k^4} + \frac{3(a_n - b_n)b_n^2}{n^6 k^2} + \frac{b_n^3}{n^6}\right) \frac{\|W\|_2^6 \|W\|_1^3}{n^6}. \end{split}$$

The proof of Proposition 2.11 is given in the supplement [57]. In Proposition 2.11, the conditions  $p_0\|W\|_1^2\gg 1$  and  $p_0^2\|W\|_1^3=o(1)$  require the hypergraph to be moderately sparse. At first glance, the conditions  $1\ll\|W\|_t^t=O(\|W\|_1)=O(n)$  for  $2\le t\le 12$  and  $\|W\|_1\asymp\|W\|_2^2$  seem very restrictive. However, these conditions are easy to satisfy and can accommodate severe degree heterogeneity. For example, when  $W_i=\frac{i}{n}$  for  $i=1,2,\ldots,n$ , we have  $\|W\|_t^t=\frac{n}{t+1}(1+o(1))$  for any positive integer t. In this case, the average degrees  $d_1$  and  $d_n$  for vertices 1 and n are

$$d_1 = \sum_{1 < j < k} W_1 W_j W_k p_0 = p_0 W_1 \left( 0.5 \left( \sum_{j=2}^n W_j \right)^2 - \sum_{j=2}^n W_j^2 \right) = \frac{np_0}{8} (1 + o(1)),$$

$$d_n = \sum_{j < k < n} W_n W_j W_k p_0$$
  
=  $p_0 W_n \left( 0.5 \left( \sum_{j=1}^{n-1} W_j \right)^2 - \sum_{j=1}^{n-1} W_j^2 \right) = \frac{n^2 p_0}{8} (1 + o(1)).$ 

Clearly,  $d_n \approx nd_1$  and hence the hypergraph is highly heterogeneous. Another example is to take  $W_i \in [c_1, c_2]$  with positive constants  $c_1 < c_2$ , which yields a hypergraph with less heterogeneous degrees.

**3. Extensions to nonuniform hypergraph.** Nonuniform hypergraph can be viewed as a superposition of a collection of uniform hypergraphs, introduced by [32] in which the authors proposed a spectral algorithm for community detection. In this section, we study the problem of testing community structure over a nonuniform hypergraph.

Let  $\mathcal{H}^k(n,M)$  be a nonuniform hypergraph over n vertices, with the vertices uniformly and independently partitioned into k communities, and  $M \geq 2$  is an integer representing the maximum length of the hyperedges. Following [32], we can write  $\mathcal{H}^k(n,M) = \bigcup_{m=2}^M \mathcal{H}^k_m(n,\frac{a_{mn}}{n^{m-1}},\frac{b_{mn}}{n^{m-1}})$ , where  $\mathcal{H}^k_m(n,\frac{a_{mn}}{n^{m-1}},\frac{b_{mn}}{n^{m-1}})$  are independent uniform hypergraphs with degree-corrected vertices introduced in Section 2.3. Correspondingly, define  $\mathcal{H}(n,M) = \bigcup_{m=2}^M \mathcal{H}_m(n,\frac{a_{mn}+(k^{m-1}-1)b_{mn}}{k^{m-1}n^{m-1}})$  as a superposition of Erdős–Rényi models. Clearly, each Erdős–Rényi model in  $\mathcal{H}(n,M)$  has the same average degree as its counterpart in  $\mathcal{H}^k(n,M)$ , and  $\mathcal{H}(n,M)$  has no community structure. Let  $A_m$  denote the adjacency tensor for m-uniform sub-hypergraph and  $A = \{A_m, m = 2, \ldots, M\}$  is a collection of  $A_m$ 's. We are interested in the following hypotheses:

(16) 
$$H_0'': A \sim \mathcal{H}(n, M) \quad \text{vs.} \quad H_1'': A \sim \mathcal{H}^k(n, M).$$

3.1. Nonuniform homogeneous hypergraphs with bounded degree. To enhance readability, we assume M=3, that is,  $\mathcal{H}=\mathcal{H}_2\cup\mathcal{H}_3$ , and the hypergraphs are homogeneous without degree correction. The results are extendable to arbitrary M with more tedious arguments. The following Corollary 3.1, extending Theorem 2.1, shows that it is impossible to distinguish  $H_0''$  and  $H_1''$  in extremely sparse regime. The proof is essentially the same as Theorem 2.1 which also relies on the conditional independence of  $\mathcal{H}_2$  and  $\mathcal{H}_3$ .

COROLLARY 3.1. If  $a_{mn} \approx b_{mn} = o(1)$ , then  $H_0''$  and  $H_1''$  are mutually contiguous.

The following Corollary 3.2 extends the bounded degree results from Section 2.2. Let  $a_{mn} = a_m$ ,  $b_{mn} = b_m$  be positive constants, and  $\kappa_m = \frac{(a_m - b_m)^2}{k^{m-1}[a_m + (k^{m-1} - 1)b_m]}$ .

COROLLARY 3.2. If  $\kappa_2 > 1$  or  $\kappa_3 > 1$ , then  $H_0''$  and  $H_1''$  are asymptotically orthogonal. If

$$\left[\kappa_2 + \frac{\kappa_3}{3}\left(1 + \frac{1}{3k^2}\right)\right](k^2 - 1) < 1,$$

then  $H_0''$  and  $H_1''$  are mutually contiguous. Furthermore, the results of Theorems 2.3 and 2.4 still hold with the corresponding quantities therein replaced by those in  $\mathcal{H}_m$ .

3.2. Nonuniform hypergraph with growing degree. Assume that, for  $2 \le m \le M$ ,  $a_{mn}$ ,  $b_{mn}$  are proxies of the hyperedge densities satisfying  $n^{l_m-1} \ll a_{mn} \times b_{mn} \ll n^{l_m-\frac{2}{3}}$ , for some integer  $1 \le l_m \le \frac{m}{2}$ .

For any  $2 \le m \le M$ , let  $\widehat{\mathcal{T}}_m$  and  $\delta_m$  be defined as in (13) and (10), respectively, based on the *m*-uniform sub-hypergraph. We define a test statistic for (16) as

(17) 
$$\widehat{\mathcal{T}} = \sum_{m=2}^{M} c_m \widehat{\mathcal{T}}_m,$$

where  $c_m$  are constants with normalization  $\sum_{m=2}^{M} c_m^2 = 1$ . As a simple consequence of Theorems 2.8 and 2.9, we get the asymptotic distribution of  $\widehat{\mathcal{T}}$  as follows.

COROLLARY 3.3. Suppose that the degree-correction weights satisfy the same conditions as in Theorem 2.8, and for any  $2 \le m \le M$ ,  $n^{l_m-1} \ll a_{mn} \times b_{mn} \ll n^{l_m-\frac{2}{3}}$ , for some integer  $1 \le l_m \le \frac{m}{2}$ . Then, as  $n \to \infty$ ,  $\widehat{\mathcal{T}} - \sum_{m=2}^M c_m \delta_m \stackrel{d}{\to} N(0,1)$ . Furthermore, for any constant C > 0, under  $H_1''$ ,  $\mathbb{P}(|\widehat{\mathcal{T}}| > C) \to 1$ , provided that  $\sum_{m=2}^M c_m \delta_m \to \infty$  as  $n \to \infty$ .

Under  $H_0''$ , that is, each *m*-uniform subhypergraph has no community structure, we have  $\delta_m = 0$  by Proposition 2.7. Corollary 3.3 says that  $\widehat{\mathcal{T}}$  is asymptotically standard normal. Hence, an asymptotic testing rule at significance  $\alpha$  would be

reject 
$$H_0''$$
 if and only if  $|\widehat{\mathcal{T}}| > z_{\alpha/2}$ .

The quantity  $\sum_{m=2}^{M} c_m \delta_m$  may represent the degree of separation between  $H_0''$  and  $H_1''$ . By Corollary 3.3, under  $H_1''$ , the test will achieve high power when  $\sum_{m=2}^{M} c_m \delta_m$  is large.

REMARK 3.1. According to Corollary 3.3, to make  $\widehat{\mathcal{T}}$  having the largest power, we need to maximize the value of  $\sum_{m=2}^{M} c_m \delta_m$  subject to  $\sum_{m=2}^{M} c_m^2 = 1$ . The maximizer is  $c_m^* = \frac{\delta_m}{\sqrt{\sum_{m=2}^{M} \delta_m^2}}$ , m = 2, 3, ..., M. The corresponding test  $\widehat{\mathcal{T}}^* = \sum_{m=2}^{M} c_m^* \widehat{\mathcal{T}}_m$  becomes asymptotically the most powerful among (17). In particular  $\widehat{\mathcal{T}}^*$  is more power-

comes asymptotically the most powerful among (17). In particular,  $\widehat{\mathcal{T}}^*$  is more powerful than  $\widehat{\mathcal{T}}_m$  for a single m. This can be explained by the additional hyperedge information involved in the test. This intuition is further confirmed by numerical studies in Section 4. Note that  $\widehat{\mathcal{T}}_2$  (m=2) is the classic test proposed by [26] in ordinary graph settings.

- **4. Numerical studies.** In this section, we provide a simulation study in Section 4.1 and real data analysis in Section 4.2 to assess the finite sample performance of our tests.
- 4.1. Simulation. We generated a nonuniform hypergraph  $\mathcal{H}^2(n,3) = \mathcal{H}^2_2(n,a_2,b_2) \cup \mathcal{H}^2_3(n,a_3,b_3)$ , with n=100 under various choices of  $\{(a_m,b_m), m=2,3\}$ . In each scenario, we calculated  $Z_2:=\widehat{T}'_2$  and  $Z_3:=\widehat{T}'_3$  by (14). Note that  $Z_2=\widehat{T}'_2$  is the test for ordinary graph considered in [26]. For testing the community structure on the nonuniform hypergraph, we calculated the statistic  $Z:=\widehat{T}=(\widehat{T}'_2+\widehat{T}'_3)/\sqrt{2}$ . In addition, we considered a strategy similar to [6] by first reducing the hypergraph to a weighted graph and applying a test designed for weighted graphs in [53]. Specifically, given an m-uniform hypergraph with hyperedges  $e_1, e_2, \ldots, e_M$ , we first transformed it to a weighted graph with an adjacency matrix  $\widetilde{A}=[\widetilde{A}_{ij}]_{1\leq i,j\leq n}$  in which  $\widetilde{A}_{ij}=\sum_{k=1}^M I(\{i,j\}\subset e_k)$  for  $i\neq j$  and  $\widetilde{A}_{ij}=0$  for i=j. In other words,  $\widetilde{A}_{ij}$  is the total number of hyperedges containing vertices i and j. Next, we

$b_3$	δ	0	1	2	3	4	5	6	7	8	9	10
0.01	-				2.93 2.71		3.38 3.16	3.58 3.35	3.75 3.53			4.21 4.02
0.005							4.75 4.61	5.08 4.97	5.38 5.31	5.67 5.64	5.94 5.94	6.20 6.24
0.001							13.95 15.51	15.39 17.26	16.76 18.92		19.28 22.00	20.48 23.46

TABLE 2 Choices of  $r_2$ ,  $r_3$ ,  $b_3$  for  $\delta$  to range from 1 to 10

generated a new weighted graph with an adjacency matrix  $A = [A_{ij}]_{1 \le i,j \le n}$  by zeroing out row s and column s of  $\widetilde{A}$  if  $\sum_{j=1}^{n} \widetilde{A}_{sj} > c_{thr} \frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{n} \widetilde{A}_{ij}$ . Here  $c_{thr} > 0$  is a prespecified threshold constant. We then applied the test method proposed by [53] to the weighted graph A, where the test statistic is denoted by  $Z_T$ .

We examined the size and power of each test by calculating the rejection proportions based on 500 independent replications at 5% significance level. Let  $\delta_m$  denote the quantity defined in (10) which is the main factor that affects power.

Our study consists of two parts. In the first part, we investigated the power change of the four testing procedures when  $\delta_2 = \delta_3 = \delta$  increases from 0 to 10. Specifically, we set  $b_2 = 10b_3$ , where  $b_3 = 0.01, 0.005, 0.001$  represents the dense, moderately dense and sparse network, respectively;  $a_m = r_m b_m$  for m = 2, 3 with the values of  $r_m$  summarized in Table 2. It can be checked that such choice of  $(a_m, b_m)$  indeed makes  $\delta$  range from 0 to 10. We also considered both balanced and imbalanced networks with the probability  $(\varsigma)$  of the smaller community takes the value of 0.5 and 0.3, respectively.

The rejection proportions under various settings are summarized in Figures 5, 6, and 7. Several interesting findings should be discussed. First, the rejection proportions of all test statistics except the  $Z_T$  (based on the graph transformation) at  $\delta = 0$  are close to the nominal level 0.05 under different choices of  $\varsigma$  and  $b_3$ , which demonstrates that these three test statistics are valid. We observe that the size (corresponding to  $\delta = 0$ ) and power (corresponding to

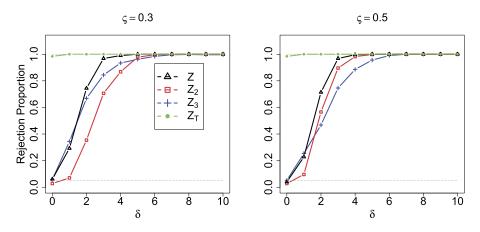


FIG. 5. Rejection proportions in dense case with  $b_3 = 0.1 \times b_2 = 0.01$ .

<sup>&</sup>lt;sup>1</sup>According to the proof of Lemmas 5 and 7 in [6],  $c_{thr}$  is a large enough constant such that  $\log(1+m^2x)-m^2 \ge \frac{1}{2}\log(x)$  for all  $x \ge c_{thr}$ . In the simulation studies, we chose  $c_{thr}$  to be the largest root of  $\log(1+m^2x)-m^2 = \frac{1}{2}\log(x)$ 

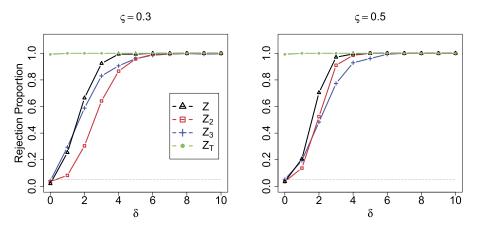


Fig. 6. Rejection proportions in moderately dense case with  $b_3 = 0.1 \times b_2 = 0.005$ .

 $\delta > 0$ ) of the graph-transformation test are almost 100% regardless of the choice of  $b_3$ , which implies that the testing procedure  $Z_T$  is asymptotically invalid. Second, as expected, the rejection proportions of all tests increase with  $\delta$ , regardless of the choices of  $b_3$  and  $\varsigma$ . Third, in most cases, the testing procedure based on nonuniform hypergraph (Z) has larger power than the one based only on the 3-uniform hypergraph ( $Z_3$ ) or the ordinary graph ( $Z_2$ ). This agrees with our theoretical finding since more information has been used in the combined test; see Remark 3.1 for a detailed explanation.

REMARK 4.1. The failure of the graph-transformation-based testing procedure  $Z_T$  is possibly due to the dependence between the edges of the transformed graph. Given the number of communities k, many existing community detection algorithms do not require the independence assumption about the edges. However, this assumption is important to derive the limit distributions of the corresponding statistics in the hypothesis testing problems about k (e.g., see [12, 26, 40, 53]). The graph-transformation-based method might still be promising for testing hypergraphs, but new asymptotic theory based on dependent edges seems necessary.

In the second part, we investigated how the powers of the tests change along with the hyperedge probability. For convenience, we report the results based on the log-scale of  $b_3$  which ranges from -8 to -6. We chose  $\delta = 1$  and  $\delta = 1$  and

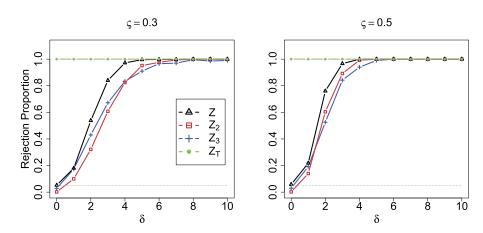


FIG. 7. Rejection proportions in sparse case with  $b_3 = 0.1 \times b_2 = 0.001$ .

δ	$\log(b_3)$	-8	-7	-6
1	$r_3$	14.18	6.88	3.93
	$r_2$	15.78	7.03	3.72
3	$r_3$	26.37	11.51	5.82
	$r_2$	30.68	12.54	5.83

TABLE 3 Choices of  $r_2$ ,  $r_3$ , and  $\delta$  for  $\log(b_3)$  to range from -8 to -6

the first part, we set  $a_m = r_m b_m$  with m = 2 and 3 to guarantee that  $\log b_3$  indeed ranges from -8 to -6. The values of  $r_m$  were summarized in Table 3. Figures 8 and 9 report the rejection proportions for  $\delta = 1$  and 3 under various hyperedge densities. We note that the rejection proportion of  $Z_T$  is always 100% under all settings. Moreover, Z is more powerful than  $Z_2$  and  $Z_3$  in the cases  $\zeta = 0.3$ , 0.5 and  $\delta = 3$ . For the remaining scenarios, all procedures have satisfactory performance.

4.2. Analysis of coauthorship data. In this section, we applied our testing procedure to study the community structure of a coauthorship network dataset, available at https://static. aminer.org/lab-datasets/soinf/. The dataset contains a 2-author ordinary graph and a 3-author hypergraph. After removing vertices with degrees less than ten or larger than 20, we obtained a hypergraph (hereinafter referred to as global network) with 58 nodes, 110 edges, and 40 hyperedges. The vertex-removal process aims to obtain a suitably sparse network so that our testing procedure is applicable. We examined our procedures based on the global network and subnetworks. To do this, we first performed the spectral algorithm proposed by [32] to partition the global network into four subnetworks which consist of 7, 13, 14, 24 vertices, respectively (see Figure 10). In Figure 11, we plotted the incidence matrices of the 2- and 3-uniform hypergraphs, denoted 2-UH and 3-UH, respectively, as well as their superposition (Non-UH). The black dots represent vertices within the same communities. The red crosses represent vertices between different communities. An edge or hyperedge is drawn between the black dots or red crosses that are vertically aligned. It is observed that the betweencommunity (hyper)edges are sparser than the within-community ones, indicating the validity of the partitioning.

We conducted testing procedures based on  $Z_2$ ,  $Z_3$ , and Z at significance level 0.05 (similar to Section 4.1) to both global network and subnetworks. The values of the test statistics are

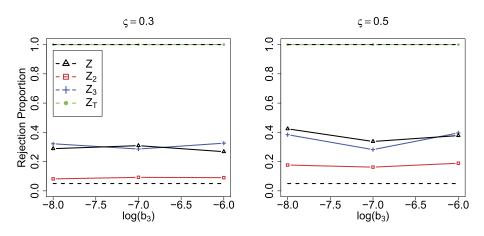


FIG. 8. Rejection proportions when  $\delta = 1$  and  $b_2 = 10b_3$ .

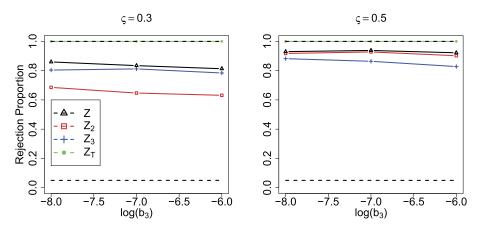


FIG. 9. Rejection proportions when  $\delta = 3$  and  $b_2 = 10b_3$ .

summarized in Table 4. Observe that  $Z_2$  and Z yield very large test values for the global network indicating strong rejection of the null hypothesis. For subnetwork testing,  $Z_2$  rejects the null hypothesis for subnetwork 3; while  $Z_3$  and Z do not reject the null hypotheses for any subnetworks. This demonstrates that the community detection results are reasonable in general, and the subnetworks may no longer have finer community structures.

**5. Discussion.** In the context of community testing for hypergraphs, we systematically considered various scenarios in terms of hyperedge densities and investigated distinguishability or indistinguishability of the hypotheses in each scenario. Extensions of our results are possible.

The first line is to extend the test statistic in Section 2.3 to tackle the model selection problem for SBM in hypergraphs. In particular, one possibility is to study the hypothesis testing problem of  $H_0: k = k_0$  vs.  $H_1: k > k_0$  for  $k_0 = 1, 2, \ldots$  sequentially and stop when observing a rejection. The second line is to extend the current results to the increasingly

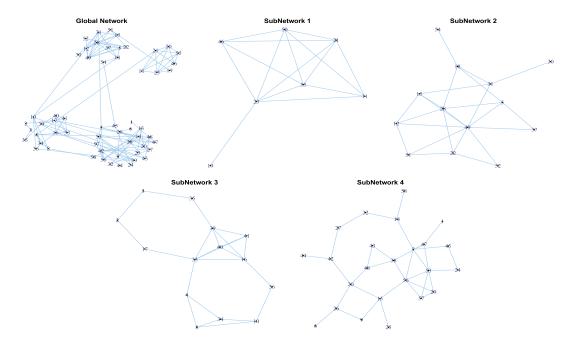


FIG. 10. Global network and four subnetworks based on coauthorship data.

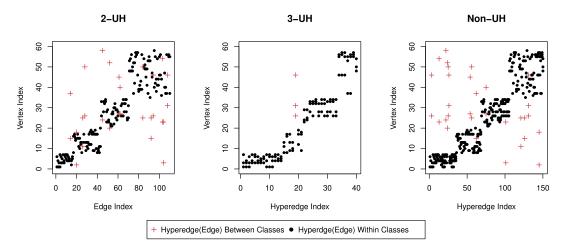


FIG. 11. Incidence matrices based on coauthorship data. Left: 2-uniform hypergraph; Middle: 3-uniform hypergraph; Right: nonuniform hypergraph.

popular degree-corrected stochastic block models. However, based on the current secondmoment technique, the bounded degree results are not easy to establish. The main reason is that the moments of the likelihood ratio do not have an explicit expression in terms of a, b,  $\kappa$ . Even in the ordinary graph setting with m = 2, this is already very difficult. To see this, when  $\sigma_i = \sigma_j$  and  $\eta_i = \eta_j$  for all i < j, it can be shown that

(18) 
$$E_{W}E_{W^{*}}\prod_{i< j}\left(\frac{p_{ij}(\sigma, W)p_{ij}(\eta, W^{*})}{p_{0}} + \frac{q_{ij}(\sigma, W)q_{ij}(\eta, W^{*})}{q_{0}}\right)$$
$$\approx E_{W}E_{W^{*}}\exp\left(\beta\sum_{i< j}(W_{i}W_{j}a - d)(W_{i}^{*}W_{j}^{*}a - d)\right),$$

where  $\beta = \frac{1}{dn^{\alpha}} + \frac{1}{n^{2\alpha}}$ . The expected value (18) seems difficult to analyze under general random weights W,  $W^*$ , even for the above special choice of  $\sigma$ ,  $\eta$ . Hence, a precise contiguity region in terms of a, b,  $\kappa$  is not available using the current second-moment method.

The third line is to test more general and complicated hypotheses. The current paper only deals with the relatively simple Erdős–Rényi null hypotheses, whereas the proposed methods may be extended to more general settings. For instance, in light of Theorem 2.3, the test statistics based on long loose cycles may also test the null hypothesis that the hypergraph is an SBM with k communities in which k > 1 is given; in light of Theorems 2.8 and 2.9, the test statistics based on sub-hypergraph counts may be extended to the null hypothesis that the model is a degree-corrected SBM with k communities. It is a worthwhile project to investigate the validity of these methods, especially in real-world situations.

Table 4 Values of test statistics based on global network and four subnetworks. Symbols \*\* and \* indicate the strength of rejection, that is, p-value < 0.001 and p-value < 0.05 respectively

	Global Network	SubNetwork 1	SubNetwork 2	SubNetwork 3	SubNetwork 4	
n	58	7	13	14	24	
$Z_2$	8.360**	0.161	-0.030	2.667*	1.661	
$Z_3^-$	1.451	-0.100	-0.211	-0.289	-0.052	
Z	6.938**	0.043	-0.171	1.682	1.137	

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## SUPPLEMENTARY MATERIAL

**Supplement to "Testing community structure for hypergraphs"** (DOI: 10.1214/21-AOS2099SUPP; .pdf). The supplementary material [57] contains all proofs to the theorems and lemmas in this paper.

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